

# Train Trajectory Generation Method to Mitigate Delay Propagation Based on Continuous Train Position Acquisition

— Stabilization of Train Operation

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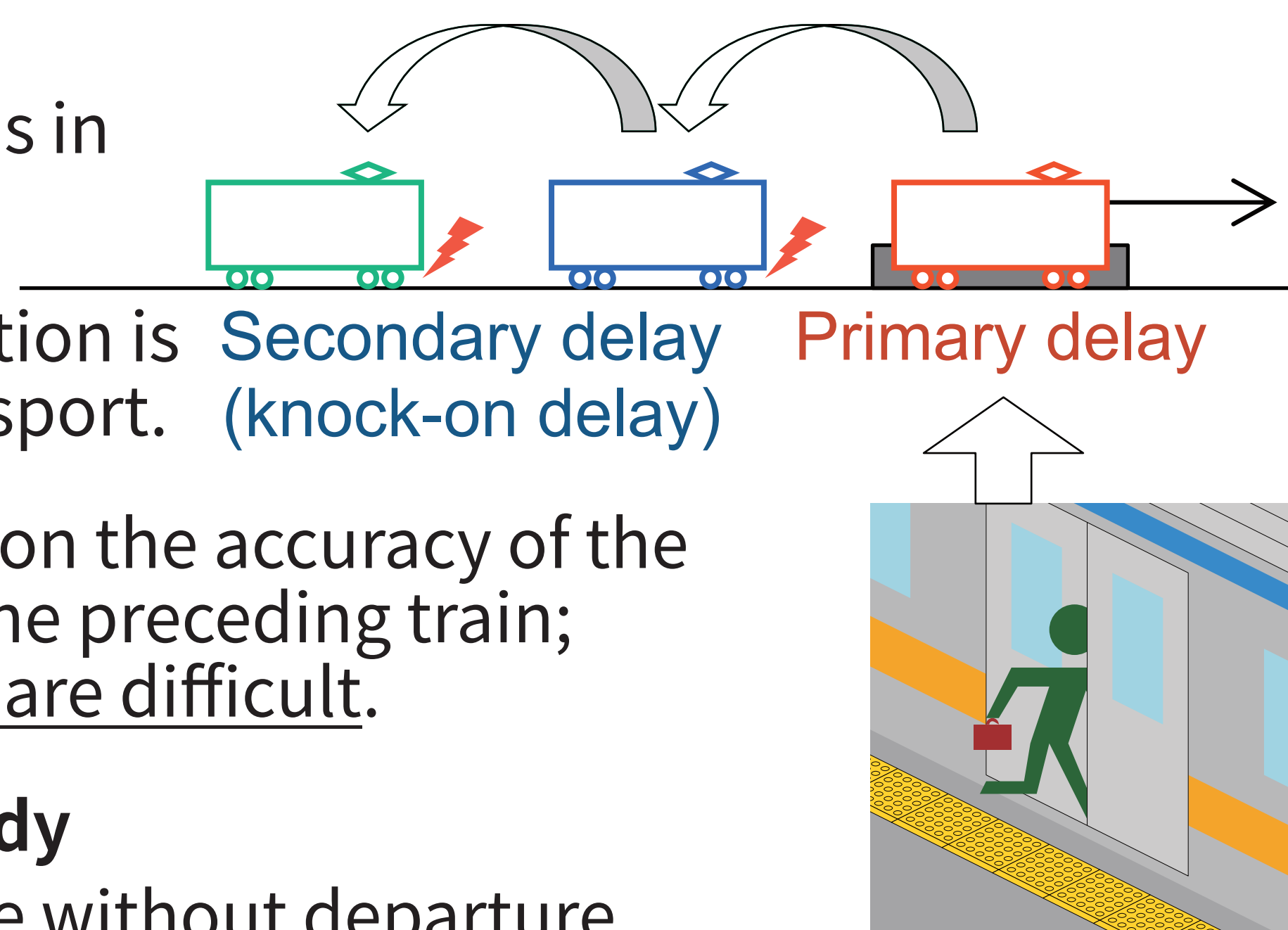
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## Background and objectives

- Train delays are easily propagated to other trains in urban railways.

- Mitigating delay propagation is important for stable transport.

- Previous studies depend on the accuracy of the departure prediction of the preceding train; however, the predictions are difficult.



### The objectives of this study

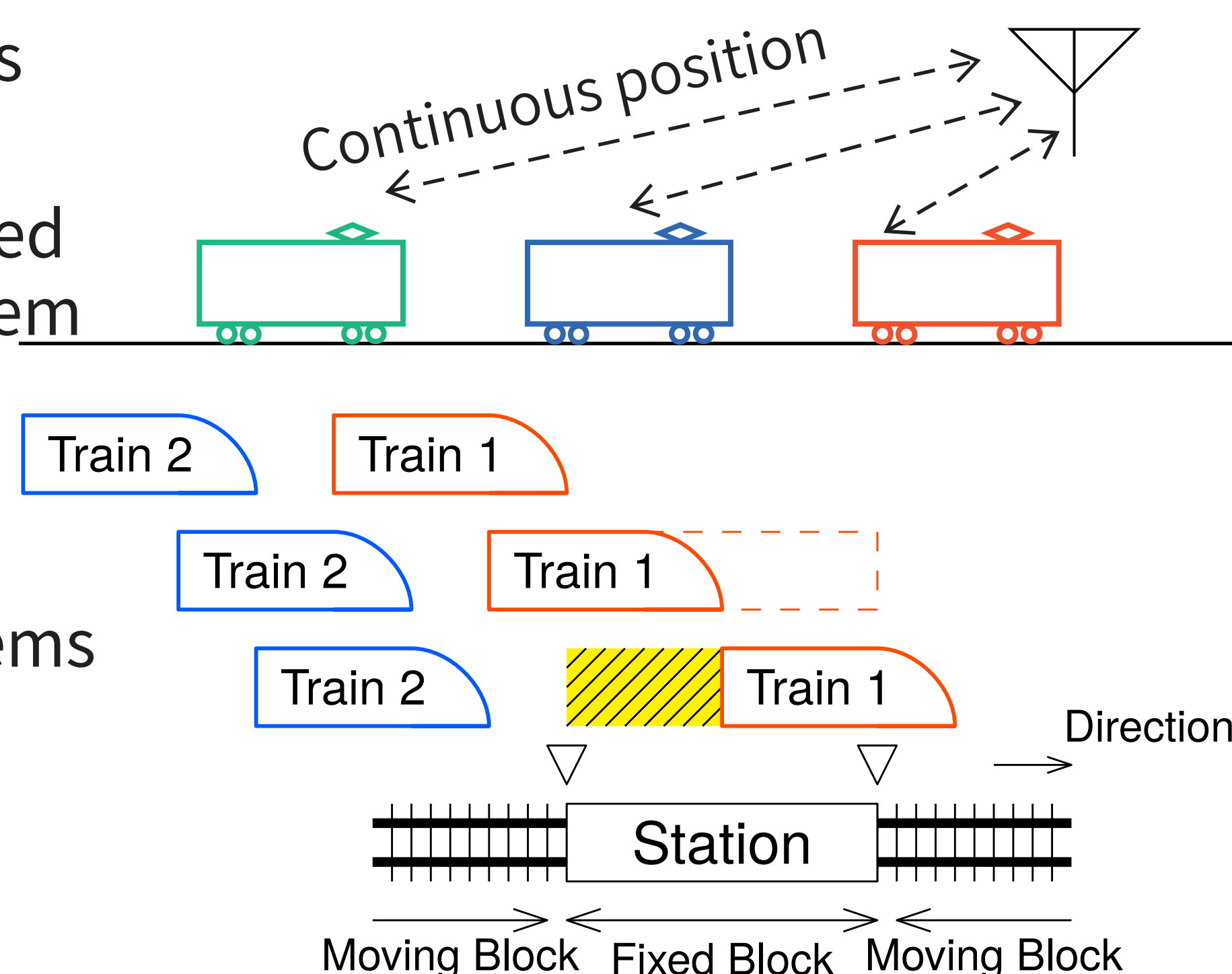
- To reduce the delay time without departure predictions.
- To reduce the duration of stopping between the stations with short-time predictions.

## Communication-Based Train Control

- Railway signaling systems prevent collisions.

- The Communication-Based Train Control (CBTC) system enables continuous train position acquisition.

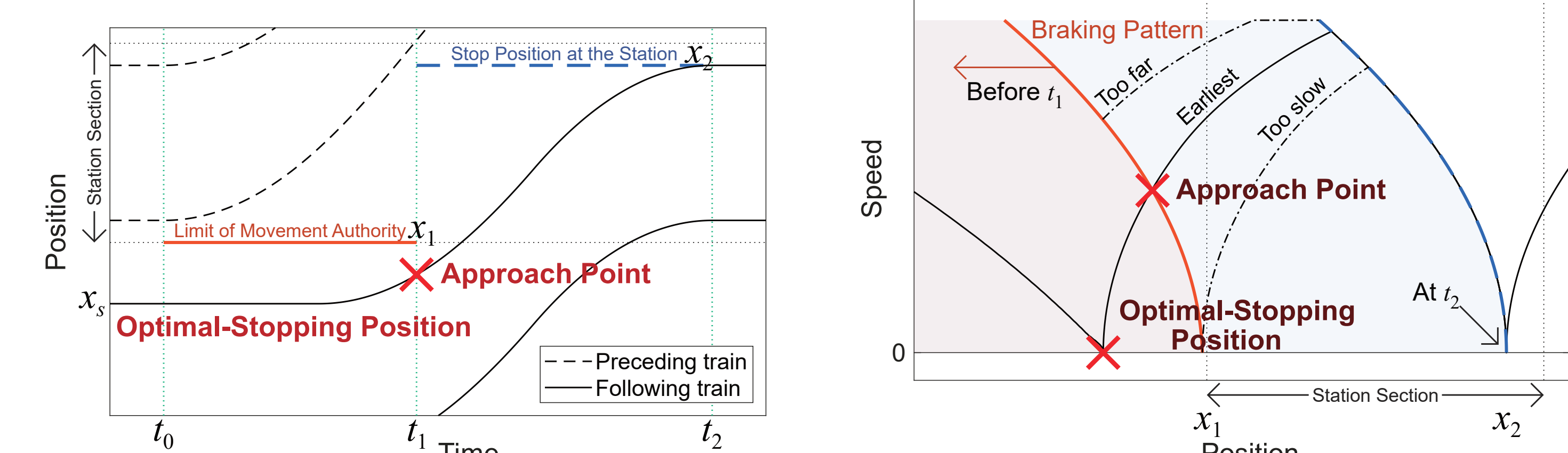
- Some existing CBTC systems consist of moving block signaling and fixed block signaling.



## Trajectory generation method

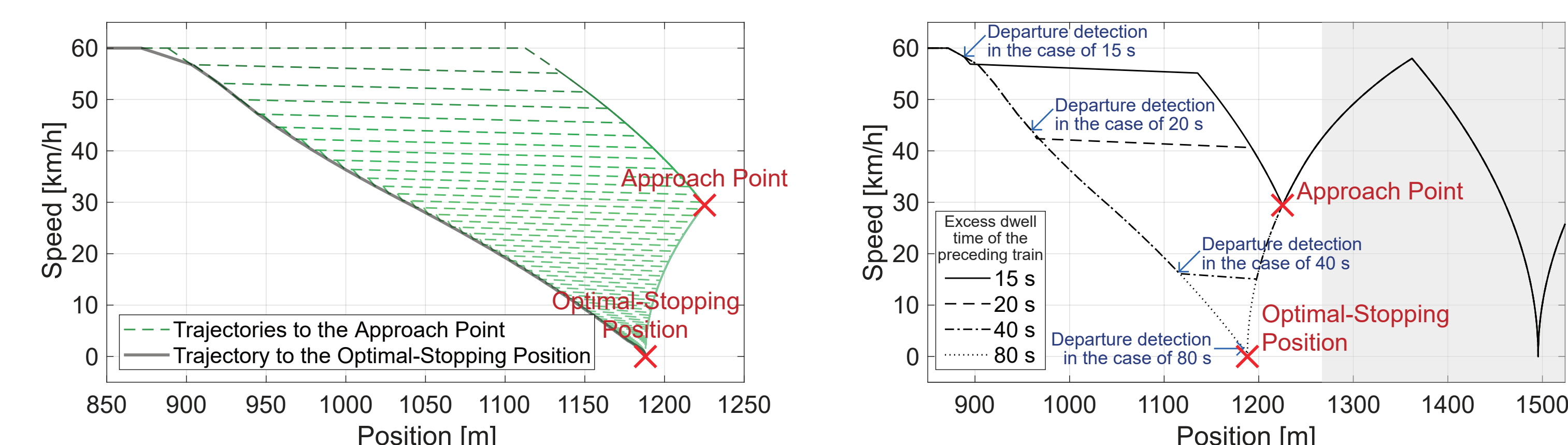
### Two optimized points

- The **approach point** is the position and speed pair at the clearing time  $t_1$ , which minimizes the departure-arrival interval (Hiraguri et al., 2004).
- The **optimal-stopping position** minimizes the energy loss due to running resistance during re-acceleration.



### Trajectory to these points

- The green dashed lines are the trajectories to the approach point.
- The gray envelope curve is the trajectory to the stopping position.



## Proposed control method

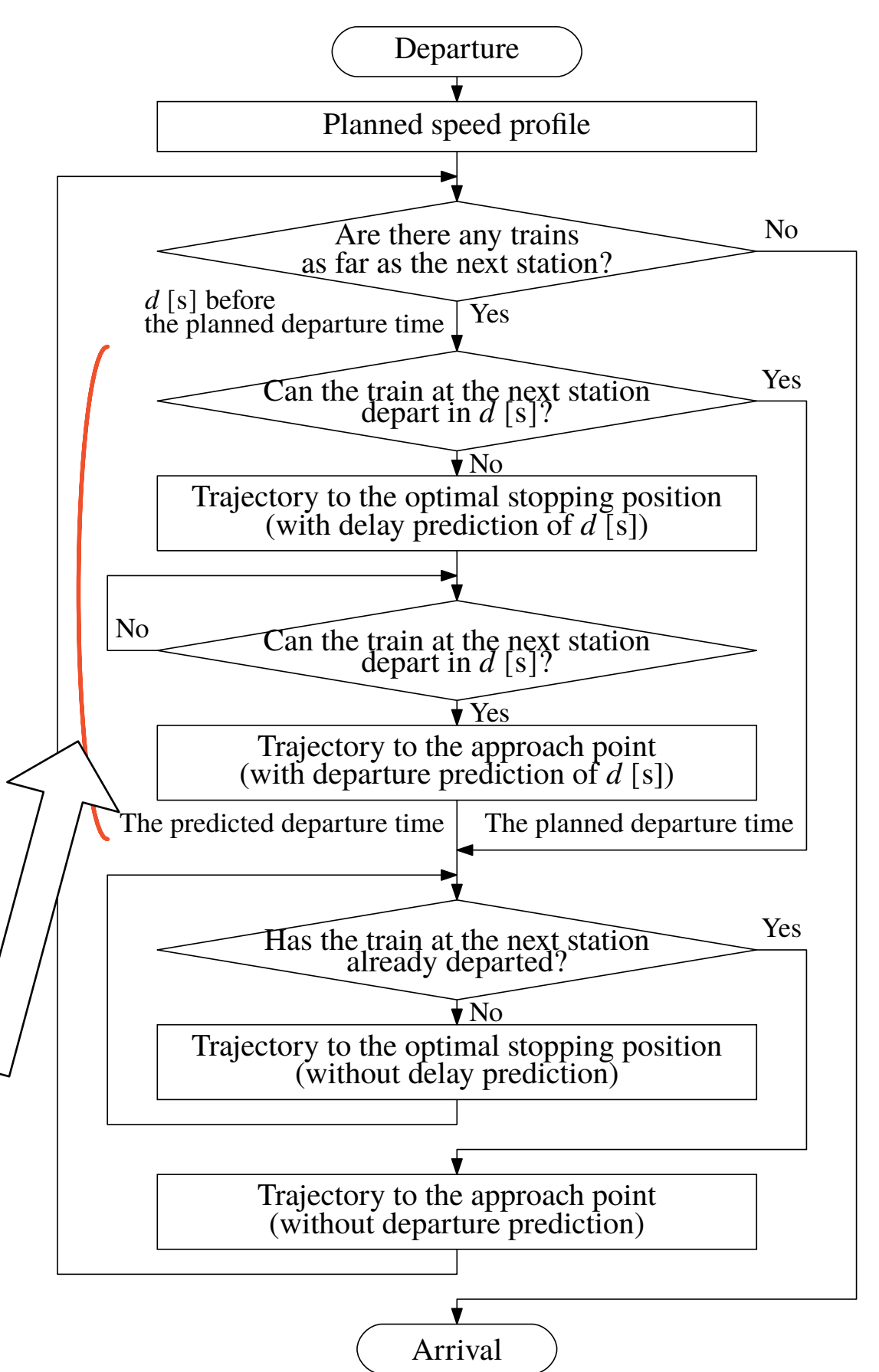
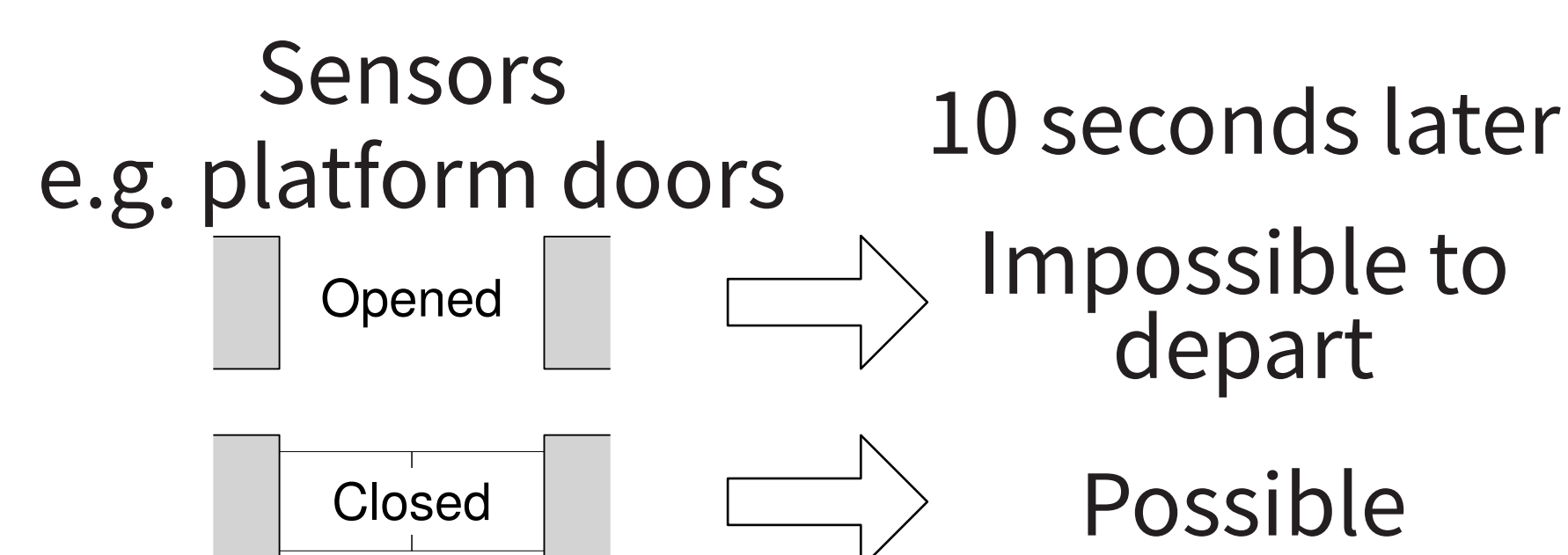
### Principle

The following train waits at the optimal position between stations.

Delay prediction ↑ Departure prediction ↓

The following train goes to the next station.

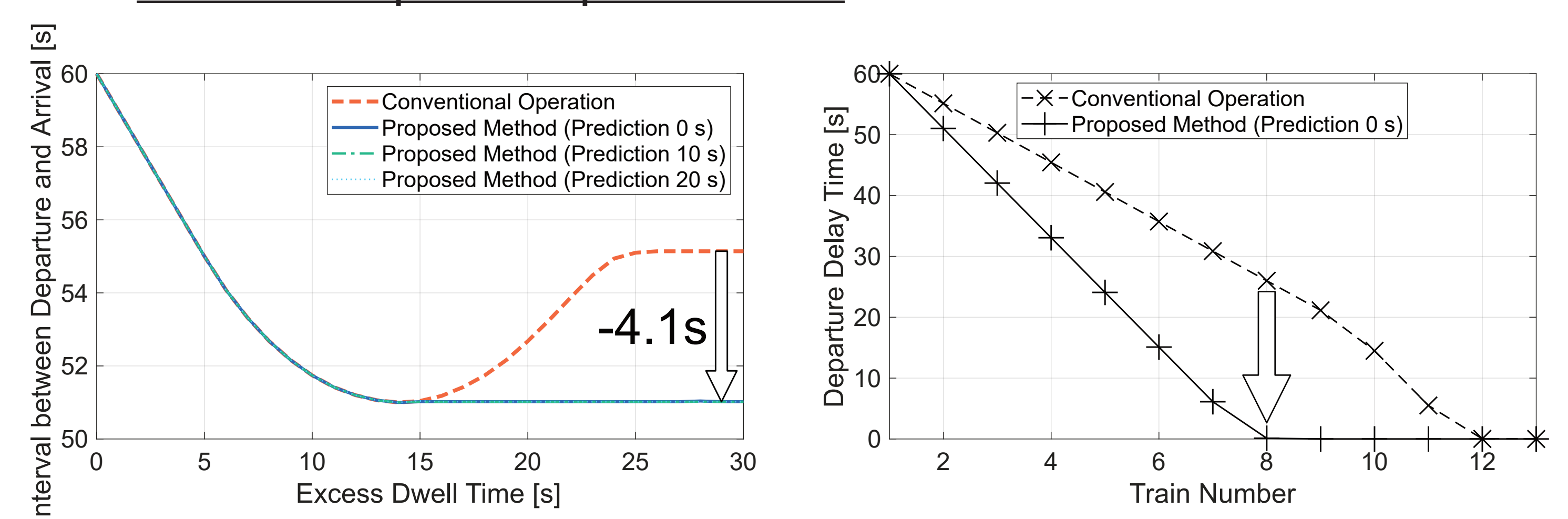
### Prediction method



## Results

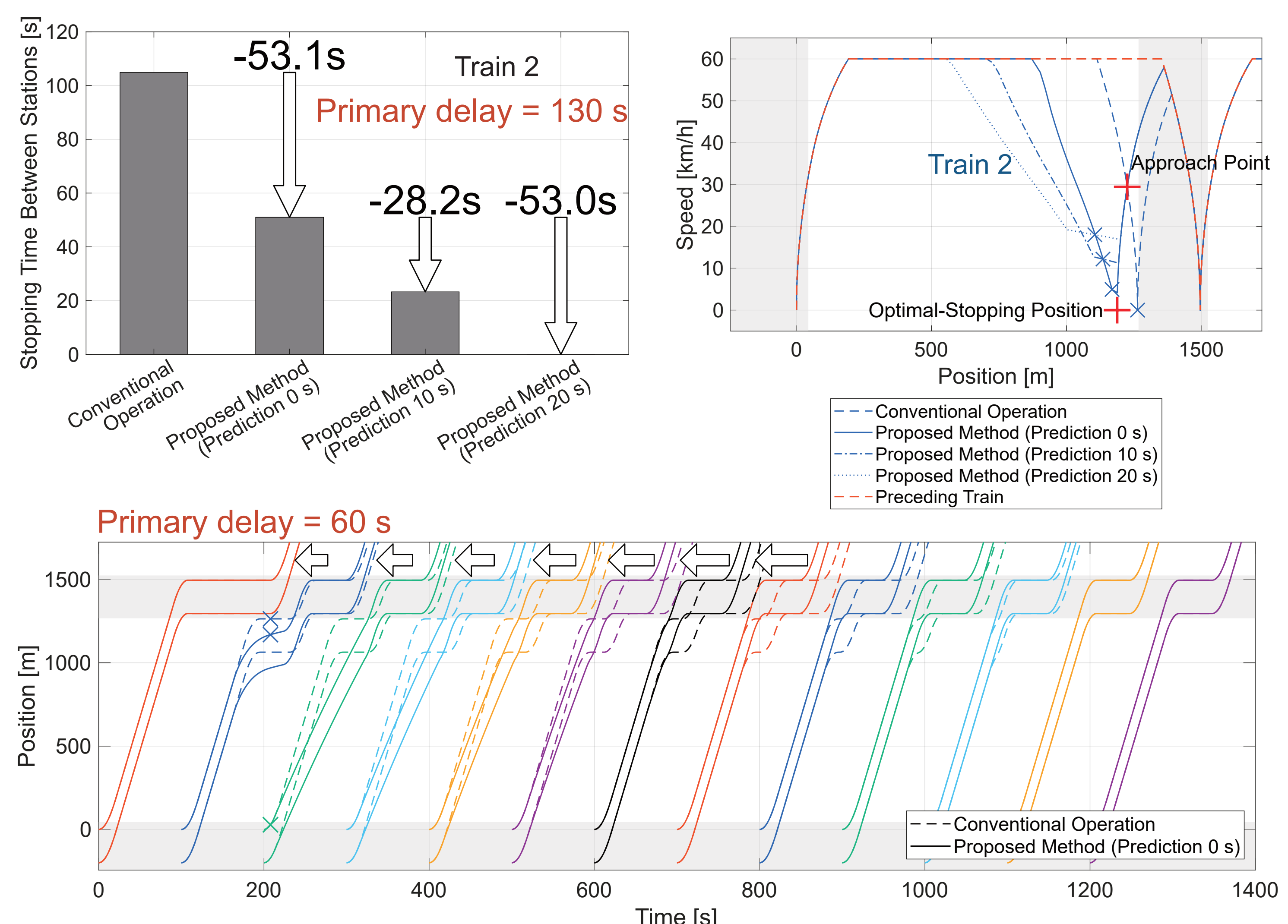
### Objective 1: the delay time

The delay propagation is mitigated as much as possible without departure predictions.



### Objective 2: the duration of stopping between stations

The proposed method with departure predictions mitigates stopping between stations as well as delay propagation.



## Conclusion

- Usefulness:** The proposed method has a practical advantage in that the driving strategy can be decided without predictions.
- Future work:** We intend to apply the proposed algorithm to the current CBTC system for on-track tests.